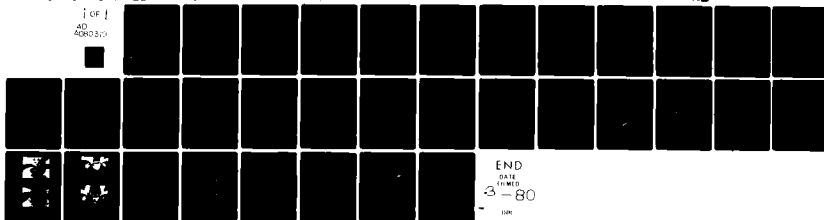


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DYNAMIC STRESS INTENSITY FACTORS FOR UNSYMMETRIC
DYNAMIC ISOCHROMATICS

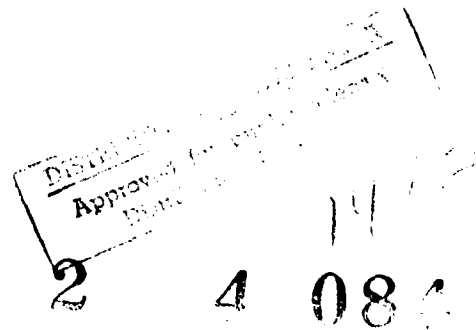
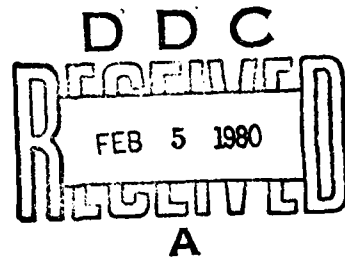
by

A. S. Kobayashi and M. Ramulu

January 1980

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Department of Mechanical Engineering
College of Engineering
University of Washington



DYNAMIC STRESS INTENSITY FACTORS FOR UNSYMMETRIC DYNAMIC ISOCHROMATICS

by

A. S. Kobayashi and M. Ramulu

University of Washington
Department of Mechanical Engineering
Seattle, Washington 98195

ABSTRACT

The mixed mode, near-field state of stresses surrounding a crack propagating at constant velocity is used to derive a relation between the dynamic stress intensity factors K_I , K_{II} , the remote stress component σ_{ox} and the dynamic isochromatics. This relation together with an overdeterministic least-square method form the basis of a data reduction procedure for extracting dynamic K_I , K_{II} and σ_{ox} from the recorded dynamic photoelastic pattern surrounding a running crack. The overdeterministic least-square method is also used to fit static isochromatics to the numerically generated dynamic isochromatics. The resultant static K_I , K_{II} , and σ_{ox} are compared with the corresponding dynamic values and estimates of errors involved in using static analysis to process dynamic isochromatic data are obtained. The data reduction procedure is then used to evaluate the branching stress intensity factor associated with crack branching and the mixed mode stress intensity factors associated with crack curving.

INTRODUCTION

In recent years, two dimensional dynamic photoelasticity has been used to determine experimentally the dynamic stress intensity factor surrounding a propagating crack and to establish a dynamic fracture toughness, K_{ID} , versus crack velocity, \dot{a} , relation which is believed to control dynamic fracture. An excellent article on this use of dynamic photoelasticity for studying

dynamic fracture has been written recently by J. W. Dally [1]*. Since fracture resistance, i.e. dynamic fracture toughness K_{ID} is equal to the driving force, i.e. instantaneous dynamic stress intensity factor, during crack propagation the dynamic stress intensity factor, which is extracted from transient dynamic isochromatics surrounding the propagating crack tip, is used to measure the dynamic fracture toughness. A commonly used data reduction procedure for this purpose is to fit a theoretical, near-field, static isochromatics to the recorded experimental dynamic isochromatics and to then equate the resultant static stress intensity factor of the former to the unknown dynamic stress intensity factor of the latter [2-5]. Error estimates for using a static near-field stress to extract the dynamic stress intensity factor have been made by several investigators [6-8] and in particular, exhaustively by Rossmanith and Irwin [8].

Studies of the static isochromatic patterns under mixed mode loading conditions, i.e. in the presence of combined K_I and K_{II} crack tip deformation, were made by Smith and Smith [9], Gdousto and Theocaris [10] and more recently by Dally and Sanford [11,12]. These isochromatics are all characterized by their unsymmetric patterns with respect to the crack line. While the simple static isochromatics used to demonstrate the importance of mixed mode loading conditions in the above references were mathematically contrived, Klein determined K_I and K_{II} from actual photoelastic patterns of a crack approaching a hole [13]. Literature, however, is scant on other mixed mode photoelastic investigations despite the well studied theoretical conditions under which such unsymmetric isochromatics can exist.

On the other hand, dynamic isochromatics surrounding a running crack often exhibits moderate unsymmetry but such photoelastic patterns were

*Number in brackets refer to Reference at the end of this paper.

heretofore considered experimental abnormalities and were ignored by averaging the unsymmetric to symmetric patterns during the data reduction process. Careful postmortem inspection of the fracture specimens, however, show that the slightly unsymmetric isochromatics are often associated with slightly curved crack propagation paths which undoubtedly are caused by the small dynamic K_{II} , coexisting with the dominating dynamic K_I value. This effects is akin to the small but noticeable influence of a small K_{II} on fatigue crack propagation reported fifteen years ago [14]. Grossly unsymmetric isochromatics associated with large crack curving, crack branching and propagating multiple cracks, on the other hand, are unmistakably caused by larger K_{II} values. The exact relation between the amount of crack curving and the dynamic K_I and K_{II} associated with the propagating crack tip would provide a dynamic crack propagation law under mixed-mode crack tip deformation similar to the K_{ID} versus Δ relation under consideration for Mode I dynamic crack propagation [15]. Since the relative magnitude of dynamic K_{II} usually is small with respect to the dynamic K_I values for many crack propagation problems, these K_{II} values must be determined accurately if a meaningful dynamic mixed-mode crack propagation law is to be deduced from these results. The purpose of this investigation is to develop a data reduction procedure for extracting K_I and K_{II} from recorded dynamic isochromatics surrounding a running crack tip. The developed procedure is also used to estimate errors involved in using static mixed-mode crack tip stress field in place of the corresponding dynamic field.

THEORY

The three stress components, σ_{xx} , σ_{yy} , and σ_{xy} in terms of the Modes I and II dynamic stress intensity factors, K_I and K_{II} , plus the remote stress component, σ_{ox} ,^{*} the maximum shear stress can be represented as [16,17,18]

^{*} Note that the sign conventions of σ_{ox} is negative of that used in References [2,7,8,11,12].

$$\tau_m^2 = \frac{1}{4} \left[H^2 \frac{1}{r} + 2H \cdot \sigma_{ox} \frac{1}{\sqrt{r}} + \sigma_{ox}^2 \right] + J^2 \frac{1}{r} \quad (1a)$$

$$\text{where } H = \frac{K_I}{\sqrt{\pi}} B_I(c) \cdot \left[(1 + s_1^2) \left\{ f(c_1) + g(c_1) \right\}^{\frac{1}{2}} - \frac{4s_1s_2}{(1 + s_2^2)} \left\{ f(c_2) + g(c_2) \right\}^{\frac{1}{2}} \right] \quad (1b)$$

$$- \frac{K_{II}}{\sqrt{\pi}} B_{II}(c) \cdot \left[(1 + s_1^2) \left\{ f(c_1) - g(c_1) \right\}^{\frac{1}{2}} - (1 + s_2^2) \left\{ f(c_2) - g(c_2) \right\}^{\frac{1}{2}} \right] \quad (1c)$$

$$J = \frac{K_I}{\sqrt{\pi}} B_I(c) \cdot s_1 \left[\left\{ f(c_1) - g(c_1) \right\}^{\frac{1}{2}} - \left\{ f(c_2) - g(c_2) \right\}^{\frac{1}{2}} \right] \quad (1d)$$

$$+ \frac{K_{II}}{4\sqrt{\pi} s_2} B_{II}(c) \cdot \left[4s_1s_2 \left\{ f(c_1) + g(c_1) \right\}^{\frac{1}{2}} - (1 + s_2^2)^2 \left\{ f(c_2) + g(c_2) \right\}^{\frac{1}{2}} \right] \quad (1e)$$

$$B_I(c) = \frac{(1 + s_2^2)}{4s_1s_2 - (1 + s_2^2)^2} \quad (1f)$$

$$B_{II}(c) = \frac{2s_2}{4s_1s_2 - (1 + s_2^2)^2} \quad (1g)$$

$$f(c_1) = \frac{1}{\sqrt{1 - \frac{c^2}{c_1^2} \sin^2 \theta}}$$

$$f(c_2) = \frac{1}{\sqrt{1 - \frac{c^2}{c_2^2} \sin^2 \theta}} \quad (1h)$$

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$$g(c_1) = \frac{\cos \theta}{1 - \frac{c^2}{c_1^2} \sin^2 \theta}$$

$$g(c_2) = \frac{\cos \theta}{1 - \frac{c^2}{c_2^2} \sin^2 \theta} \quad (1i)$$

$$s_1^2 = 1 - \frac{c^2}{c_1^2}$$

$$s_2^2 = 1 - \frac{c^2}{c_2^2} \quad (1j)$$

r and θ are the traditional polar-coordinates with origin at the moving crack tip and c , c_1 , and c_2 are the crack velocity, dilatational and distortional wave velocities, respectively.

For each given θ the radial distance, r , can be explicitly solved from equation (1a) for a given crack velocity, c , mixed mode dynamic stress intensity factors of K_I and K_{II} , and remote stress component of σ_{ox} . Thus the theoretical isochromatics τ_m for a straight crack propagating under constant velocity can be easily constructed. When equation (1) is used to extract K_I and K_{II} from recorded dynamic isochromatics, one can generate 9000 plus isochromatic loops for various combinations of K_I , K_{II} , and σ_{ox} following Etheridge et al. [19] and use a search routine to match the computer stored isochromatics with the experimental isochromatics. In this paper, however, the direct and overdeterministic procedure, which was developed by Bradley [3] and updated with improved numerical techniques by Sanford et al. [12], of least square fitting equation (1) to a large number of measured isochromatic data point is used.

For the above overdeterministic method of least square fitting a theoretical isochromatics τ_m at coordinate locations (r_k, θ_k) , equation (1) can be rewritten in a functional form, F_k , which represents the deviation between the square of the calculated and measured isochromatics

$$F_k = \frac{1}{4} \left[H_k^2 \frac{1}{r_k} + 2H_k \sigma_{ox} \frac{1}{\sqrt{r_k}} + \sigma_{ox}^2 \right] + J_k^2 \frac{1}{r_k} - \tau_m^2 \quad (2)$$

where $k = 1, 2, \dots$, is the number of data points on the recorded isochromatic.

Obviously $F_k = 0$ when the theoretical and measured isochromatic coincides.

In general, such coincidence cannot be expected and thus K_I , K_{II} and σ_{ox} must be optimized in order to minimize the total summation of F_k . For such minimization, consider:

$$\frac{\partial F_k}{\partial K_I} = \frac{1}{4} \left[2H_k \frac{\partial H_k}{\partial K_I} \frac{1}{r_k} + 2 \frac{\partial H_k}{\partial K_I} \sigma_{ox} \frac{1}{\sqrt{r_k}} \right] + 2J_k \frac{\partial J_k}{\partial K_I} \frac{1}{r_k} \quad (3a)$$

$$\frac{\partial F_k}{\partial K_{II}} = \frac{1}{4} \left[2H_k \frac{\partial H_k}{\partial K_{II}} \frac{1}{r_k} + 2 \frac{\partial H_k}{\partial K_{II}} \sigma_{ox} \frac{1}{\sqrt{r_k}} \right] + 2J_k \frac{\partial J_k}{\partial K_{II}} \frac{1}{r_k} \quad (3b)$$

$$\frac{\partial F_k}{\partial \sigma_{ox}} = \frac{1}{2} \left[H_k \frac{1}{\sqrt{r_k}} + \sigma_{ox} \right] \quad (3c)$$

$$\text{where } \frac{\partial H_k}{\partial K_I} = \frac{1}{\sqrt{\pi}} B_I \cdot \left[(1 + s_1^2) \left\{ f(c_1) + g(c_1) \right\}^{\frac{1}{2}} - \frac{4s_1 s_2}{(1 + s_2^2)} \left\{ f(c_2) + g(c_2) \right\}^{\frac{1}{2}} \right] \quad (3d)$$

$$\frac{\partial H_k}{\partial K_{II}} = \frac{-1}{\sqrt{\pi}} B_{II} \cdot \left[(1 + s_1^2) \left\{ f(c_1) - g(c_1) \right\}^{\frac{1}{2}} - (1 + s_2^2) \left\{ f(c_2) - g(c_2) \right\}^{\frac{1}{2}} \right] \quad (3e)$$

$$\frac{\partial J_k}{\partial K_I} = \frac{1}{\sqrt{\pi}} B_I \cdot s_1 \cdot \left[\left\{ f(c_1) - g(c_1) \right\}^{\frac{1}{2}} - \left\{ f(c_2) - g(c_2) \right\}^{\frac{1}{2}} \right] \quad (3f)$$

$$\frac{\partial J_k}{\partial K_{II}} = \frac{1}{4\sqrt{\pi}} \frac{B_{II}}{s_2} \left[4s_1 s_2 \left\{ f(c_1) + g(c_1) \right\}^{\frac{1}{2}} - (1 + s_2^2)^2 \left\{ f(c_2) + g(c_2) \right\}^{\frac{1}{2}} \right] \quad (3g)$$

The subsequent steps of extracting the optimized K_I , K_{II} , and σ_{ox} using the least square method is a standard numerical procedure which is also identical to that of Reference [12] and thus will not be repeated. Basically, the procedure consists of a sequence of error reduction estimates ΔK_I , ΔK_{II} , and $\Delta \sigma_{ox}$ starting from an initially estimated K_I , K_{II} , and σ_{ox} . The numerical procedure has considered to converge when the current ΔK_I , ΔK_{II} , and $\Delta \sigma_{ox}$ are less than 0.1% of the previously calculated K_I , K_{II} and σ_{ox} .

THEORETICAL ISOCHROMATICS

As one checks on the accuracy of equation (1), the dynamic isochromatics should coincide with that of Reference [11] in the limiting case of crack velocity $c \rightarrow 0$. Also informative would be a comparison between this static isochromatics and the corresponding dynamic isochromatics for the identical K_I , K_{II} , and σ_{ox} for a given crack velocity.

In order to provide such theoretical comparison, theoretical isochromatics were generated using the same model fringe constant of $f_\sigma/h = 1.73$ MPa/fringe (250 psi/fringe), $K_I = .879$ MPa \sqrt{m} (800 psi \sqrt{in}) and K_{II} of Reference [12]. Static isochromatics were approximated by setting $c = 0.0001 c_1$ in equation (1). A constant crack velocity of $c = 0.15 c_1$ was chosen to generate the dynamic isochromatics. In addition $c_1 = 2,400$ m/sec (94,300 in/sec) and $c_2 = 1,160$ m/sec (45,800 in/sec) were assumed in the dynamic analysis. In the following some representative static and dynamic isochromatics, which were originally plotted on a CALCOM plotter and then inked for presentation, are shown.

Mode I static and dynamic isochromatics have been studied by others [6,8,20] and thus many of the sample calculations in these references were reproduced as a partial check of the computer code developed for plotting dynamic isochromatics. In particular, the dynamic isochromatics generated in Reference [20] were all reproduced with the new algorithm and the two

results agreed within 0.01 percent. For comparison purpose, some of the results of pure Mode I, pure Mode II and mixed-mode static isochromatics in Reference [12] together with their dynamic counterpart are listed in the following.

Figures 1, 2 and 3 show typical static and dynamic isochromatics of fringe orders, 2.5 and 3.5 surrounding a crack tip. As amply discussed by others [7, 8, 11], for negative values of σ_{ox} the isochromatics lean forward in the direction of crack propagation while for positive values of σ_{ox} the isochromatics lean backward away from the direction of crack propagation. The static isochromatics in Figure 1 coincides with that in Figure 4 of Reference [11]. Figures 2 and 3 show further backwards leaning isochromatics which are due to the higher $\sigma_{ox}/K_I = 0.5$ and 0.75 . As shown in this figure, the differences between the static and dynamic isochromatics are small for forward leaning loops in Figure 1 but increase slightly with increase in backward leaning angles in Figures 2 and 3.

Figure 4 shows the static and dynamic isochromatics of $N = 2.5$ and 3.5 for a pure Mode II crack tip deformation. The static results are in agreement with that in Figure 5 of Reference [11]. Unlike the pure Mode I crack tip deformation, little difference between the static and dynamic isochromatics is observed. Experimentally, a crack has seldom been observed to propagate in a straight line under pure Mode II crack tip deformation but will generally curve* to achieve a maximum K_I with attendant smaller K_{II} . Thus a pure Mode II dynamic isochromatic may be a mute academic study. Pure Mode II isochromatics of a stationary crack were reported in Reference [21].

*Since the near-field dynamic stress field used to generate the dynamic isochromatics of equation (1a) is for a straight crack, the extent of near-field for a curved crack must be reduced accordingly for this straight crack approximation to hold.

Probably the most frequently encountered mixed-mode static and dynamic isochromatics are generated by the presence of relatively small K_{II} and σ_{ox} coexisting with the K_I mode of crack tip deformation. Figure 5 shows a typical asymmetric isochromatic patterns where some differences between the static and dynamics isochromatics are noted. Figure 6 shows significant change in isochromatic patterns when the sign of the remote stress component σ_{ox} is changed. Needless to say the static isochromatics coincide with those in Figures 8a and 8c, respectively in Reference [11].

Other static isochromatic patterns shown in Reference [11] together with the corresponding dynamic isochromatics were also generated mainly to verify the computer plotted isochromatics for $c = 0.0001 c_I$ cases. Details of the changes in the shapes of the static isochromatics are discussed thoroughly in Reference [11] and thus will not be reproduced here. In essence the corresponding dynamic isochromatics are found to be slightly larger and essentially follow the general shape of the static isochromatics similar to results shown in Figures 1 through 6.

ERROR ANALYSIS

As mentioned previously, the basic data reduction procedure developed in this investigation consists of least-square-fitting the mixed mode, dynamic near-field state of stress to a large number of data points of a dynamic isochromatic field. For a known constant crack velocity then, this overdeterministic numerical procedure provided the associated dynamic K_I , K_{II} , and σ_{ox} . Internal consistency of this procedure was first verified by least-square fitting a dynamic isochromatic every $\theta_k = 18, 36, \dots, 360$, to the theoretical dynamic isochromatic generated for given K_I , K_{II} , and σ_{ox} and then recovering these three dynamic parameters through the overdeterministic method. The recovered K_I , K_{II} and σ_{ox} were within 0.1% of their original values for all five cases represented by Figures 1 through 6.

The differences in static and dynamic isochromatics for the commonly observed maximum crack velocity of about $c = 0.15 c_1$, as shown in Figures 1 through 6, are relatively small. Nevertheless, a quantitative assessment of the error involved in using static analysis to extract dynamic K_I and K_{II} is necessary since static analysis has been used extensively for reducing the dynamic photoelasticity data associated with a running crack.

Errors involved in using a three-parameter static near-field state of stress to characterize a dynamic isochromatic field associated with a constant velocity crack were estimated by least square fitting a static isochromatics (i.e. $c = 0.0001 c_1$) to theoretical dynamic isochromatics which were generated through the use of equation (1). The commonly used data reduction procedure was simulated by least square fitting the static field at; 1) three points of θ_{max}^* and $\theta_{max} \pm 6^\circ$ along the two dynamic isochromatic lobes on both sides of the crack and 2) along 10 points each straddling θ_{max} and between the maximum width of the two isochromatic lobes on both sides of the arch. The difference between the resultant static K_I , K_{II} , and σ_{ox} and the corresponding dynamic values then constitute the theoretical errors involved in using the static near-field isochromatics for data reduction.

Figure 7 shows the progressive increase in error with increased crack velocity for pure Mode I crack tip deformation. Only the 20 point, i.e. 10 points each on each of the two symmetric isochromatic lobes, data fitting procedure was used for obtaining these results as well as those in Figure 7. Figure 7 shows that errors involved in the overdeterministic method of least-square fitting the near-field static isochromatics of two parameters, K_I and σ_{ox} with $K_{II} = 0$, does not differ substantially with σ_{ox} , with the exception

* For definition of θ_{max} , see References [2,3,5,7,8].

of $\sigma_{ox}/K_I = \pm 0.75$, in the crack velocity range of $c/c_I < 0.2$ and this finding is in agreement with that of Reference [7]. The lack of systematic changes in errors, i.e. for $\sigma_{ox}/K_I = \pm 0.75$ is an indication that the optimization process involved in the least-square method is functioning properly. Significant, however, is the systematic increase in the error amounting to 13-24 percent of the correct dynamic values at extremely high crack velocity of $c = 0.25 c_I$. For a crack velocity of $c/c_I = 0.15$ the estimated errors shown in Figure 7 are within 2-4 percent of those of Rossmanith and Irwin [8] who conducted a more extensive error analysis involved with Mode I dynamic crack propagation.

In the unlikely event of a dynamic crack propagation under pure Mode II crack tip deformation, a two parameter static stress field, K_{II} and σ_{ox} with $K_I = 0$, can be fitted to this dynamic isochromatics. The errors involved in the fitting process is shown in Figure 8. Unlike the pure Mode I crack tip deformation, the errors involved in using the static near-field stress are small as may have surmised from Figure 4.

Errors estimation in fitting a static near-field mixed mode isochromatic to a mixed-mode dynamic isochromatic will obviously vary with the relative magnitudes of K_I , K_{II} and σ_{ox} . In order to estimate such errors, the static three parameter stress field was least-square fitted to an arbitrary mixed-mode, dynamic isochromatic associated with $K_I = .879 \text{ MPa } \sqrt{m} \text{ (800 psi } \sqrt{in})^*$ and $K_{II} = .219 \text{ MPa } \sqrt{m} \text{ (200 psi } \sqrt{in})^*$ with varying σ_{ox} . Figures 9a and 9b show the widely varying errors in the K_I and K_{II} determined by such optimization procedure. Of particular concern is the unpredicted large errors in K_I and K_{II} associated with higher crack velocities. While this large error could in part be due to the distorted shape of isochromatics as shown in Figure 6,

*These values were selected from Reference [11].

these results nevertheless indicate the importance of using the dynamic near field stress for extracting dynamic K_I and K_{II} when the isochromatics are distorted.

EXAMPLES

The developed computer code for computing dynamic K_I , K_{II} , and σ_{ox} was then used to determine the dynamic K_I and K_{II} from the dynamic isochromatics associated with a curving crack and a branching crack.

Figure 10 shows two frames out of a 16-frame dynamic photoelastic record of a curving crack impacting a 12.7 mm (1/2-inch) diameter hole in a 9.53 mm (3/8-inch) thick, 254 x 254 mm (10 x 10 inch) Homalite-100 plate loaded under fixed gripped tension. The crack emanated from a small precrack at the top edge of plate upon reaching a critical load and propagated slightly off the centerline until it was pulled into the higher tension field surrounding the hole. Further details of the experimental setup, crack velocity measurements and dynamic calibration of the Homalite-100 material used are found in Reference [22].

Figure 11 shows three frames out of a 16-frame dynamic photoelastic record of a crack propagating and branching in a 3.18 mm (1/8-inch) thick, 254 x 254 mm (10 x 10 inch) Homalite-100 plate loaded under fixed-gripped tension. Again details of the experiment can be found in Reference [22].

Figure 12 shows the dynamic K_I and K_{II} variations obtained from the four dynamic photoelastic patterns preceding crack curving and crack impacting the hole as shown in Figure 10. Although not conclusive, the ratio of dynamic K_{II}/K_I increases rapidly prior to crack curving, thus leading to a natural speculation that a moderately mixed mode local dynamic state of stress results in curving of a propagating crack.

Figure 13 shows the dynamic K_I and K_{II} for three branches of the cracks shown in Figure 11. While the continuous "right branch" crack shows moderate changes in dynamic K_I and K_{II} , the left branch shows a sharp drop in dynamic K_I after crack branching. By extrapolating the dynamic K_I s associated with "left branches Nos. 1 and 2", an after-branching dynamic stress intensity factor of $0.923 \text{ MPa } \sqrt{\text{m}}$ ($840 \text{ psi } \sqrt{\text{in}}$) is obtained. The branching stress intensity factor, i.e. immediately prior to branching, is estimated to be $2.03 \text{ MPa } \sqrt{\text{m}}$ ($1850 \text{ psi } \sqrt{\text{in}}$). Although this singular data is higher than the branching stress intensity factor of $1.38 \text{ MPa } \sqrt{\text{m}}$ ($1250 \text{ psi } \sqrt{\text{in}}$) quoted in Reference [1], the ratio of $2.03/0.923 = 2.2$ is consistent with the postulate crack branching occurs to dissipate fracture energy along two propagating cracks. It is also interesting to note that dynamic K_{II} which is a relatively low $0.11 \text{ MPa } \sqrt{\text{m}}$ ($100 \text{ psi } \sqrt{\text{in}}$) prior to crack branching nearly doubles immediately after crack branching and is consistent with the static results of Reference [23].

CONCLUSIONS

1. A data reduction scheme for evaluating the unsymmetric dynamic isochromatic associated with dynamic mixed-mode crack propagation has been developed.
2. Errors involved in using a mixed-mode static near-field stress to evaluate dynamic K_I and K_{II} from a dynamic unsymmetric isochromatics could be larger than that involved for pure Mode I or pure Mode II crack tip deformation.
3. The utility of the developed data reduction procedure was demonstrated.

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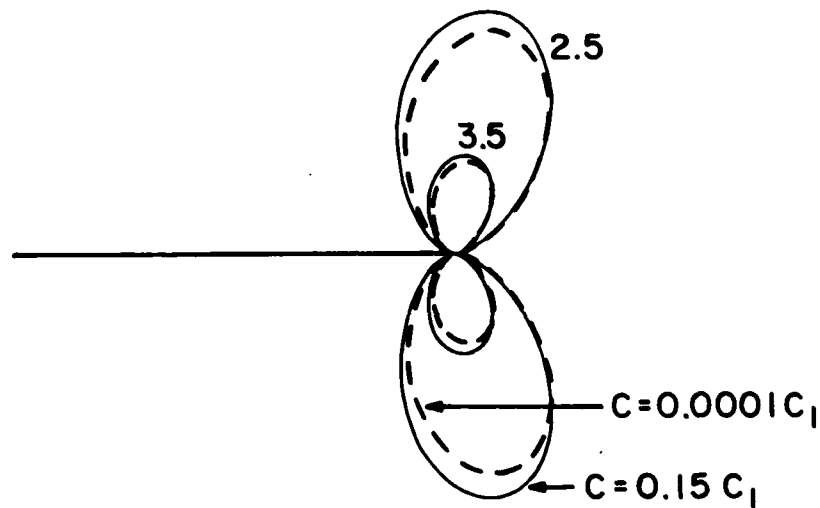


FIGURE 1. STATIC AND DYNAMIC ISOCHROMATICS NEAR A
STATIONARY ($C=0.0001C_I$) AND PROPAGATING
($C=0.15C_I$) CRACK TIP.

$$K_I = 800 \text{ psi} \sqrt{\text{in}}, K_{II} = 0, \sigma_{ox} = -0.25 K_I \text{ psi}$$

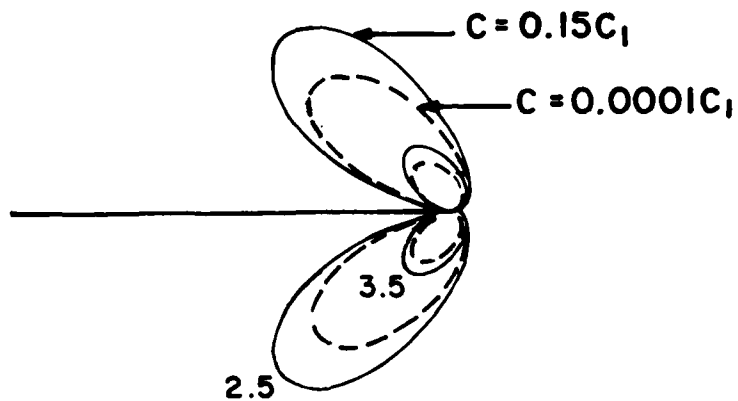


FIGURE 2. STATIC AND DYNAMIC ISOCHROMATICS NEAR A STATIONARY ($C=0.0001C_I$) AND PROPAGATING ($C=0.15C_I$) CRACK TIP.

$K_I=800\text{psi}\sqrt{\text{in}}$, $K_{II}=0$, $\sigma_{ox} = 0.5K_I\text{psi}$.

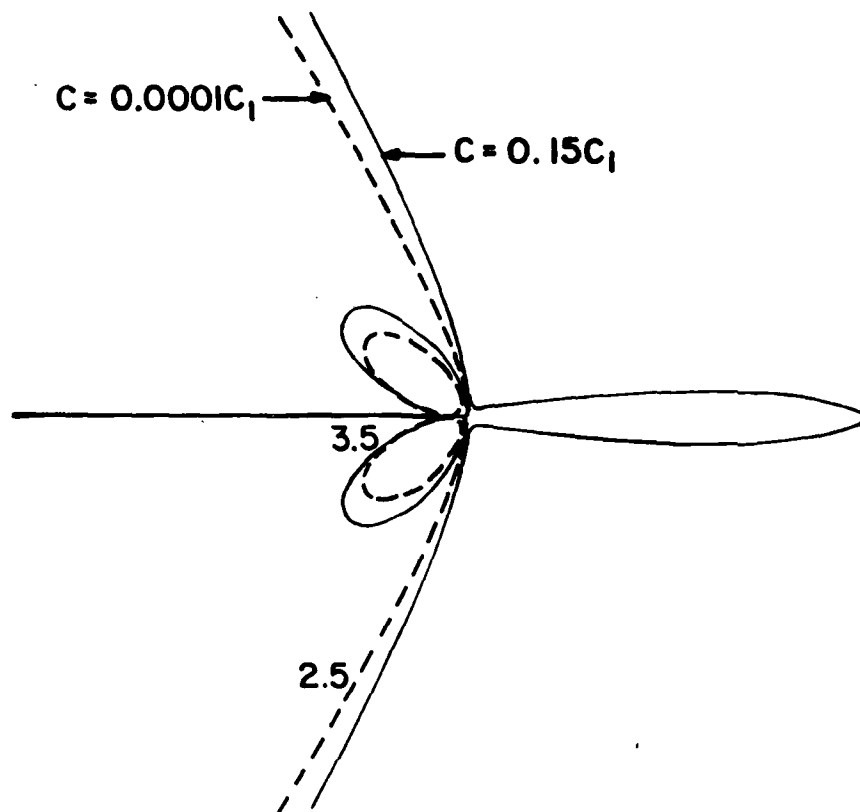


FIGURE 3. STATIC AND DYNAMIC ISOCHROMATICS NEAR A
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 ($C=0.15C_I$) CRACK TIP.
 $K_I = 800 \text{ psi}\sqrt{\text{in}}$, $K_{II} = 0$, $\sigma_{ox} = 0.75 K \text{ psi}$.

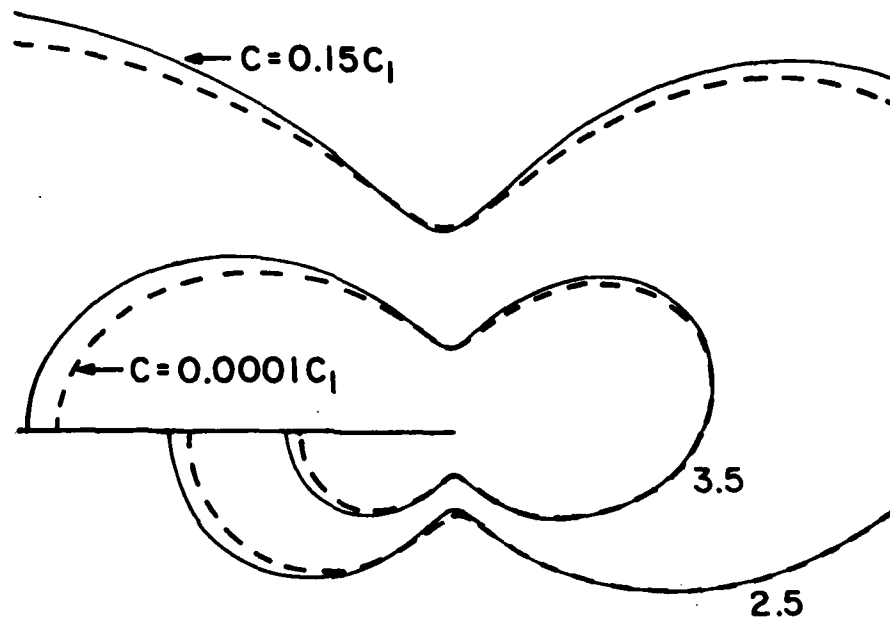


FIGURE 4. STATIC AND DYNAMIC ISOCHROMATICS NEAR A STATIONARY ($C=0.0001C_I$) AND PROPAGATING ($C=0.15C_I$) CRACK TIP.

$$K_I = 0, K_{II} = 800 \text{ psi} \sqrt{\text{in}}, \sigma_{ox} = -0.25 K_{II} \text{ psi}$$

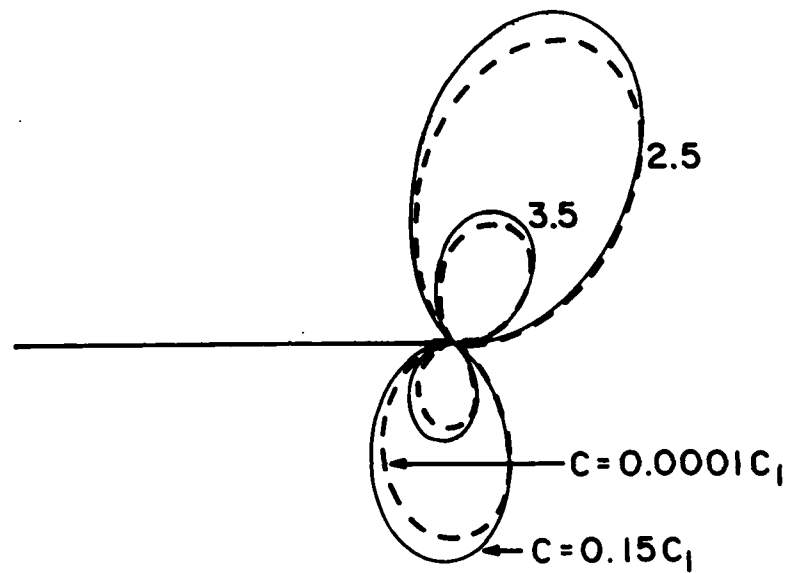


FIGURE 5. STATIC AND DYNAMIC ISOCHROMATICS NEAR A
 STATIONARY ($C=0.0001C_I$) AND PROPAGATING
 ($C=0.15C_I$) CRACK TIP.
 $K_I = 800 \text{ psi} \sqrt{\text{in}}$, $K_{II} = 0.25 K_I \text{ psi} \sqrt{\text{in}}$, $\sigma_{ox} = -0.25 K_I \text{ psi}$

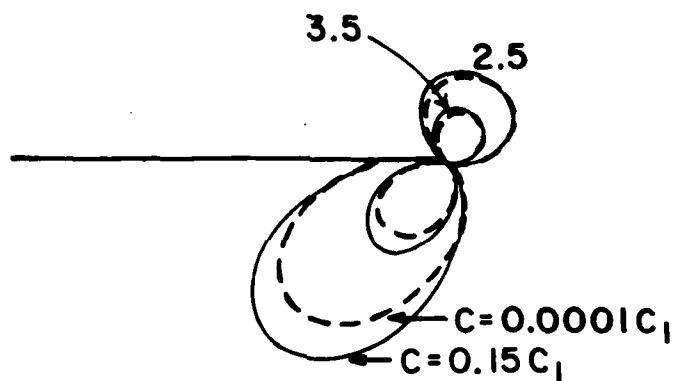


FIGURE 6. STATIC AND DYNAMIC ISOCHROMATICS NEAR
 A STATIONARY ($C=0.0001C_I$) AND PROPAGATING
 ($C=0.15C_I$) CRACK TIP.
 $K_I = 800 \text{ psi}\sqrt{\text{in}}$, $K_{II} = 0.25 K_I \text{ psi}\sqrt{\text{in}}$, $\sigma_{ox} = -0.25 K_I \text{ psi}$

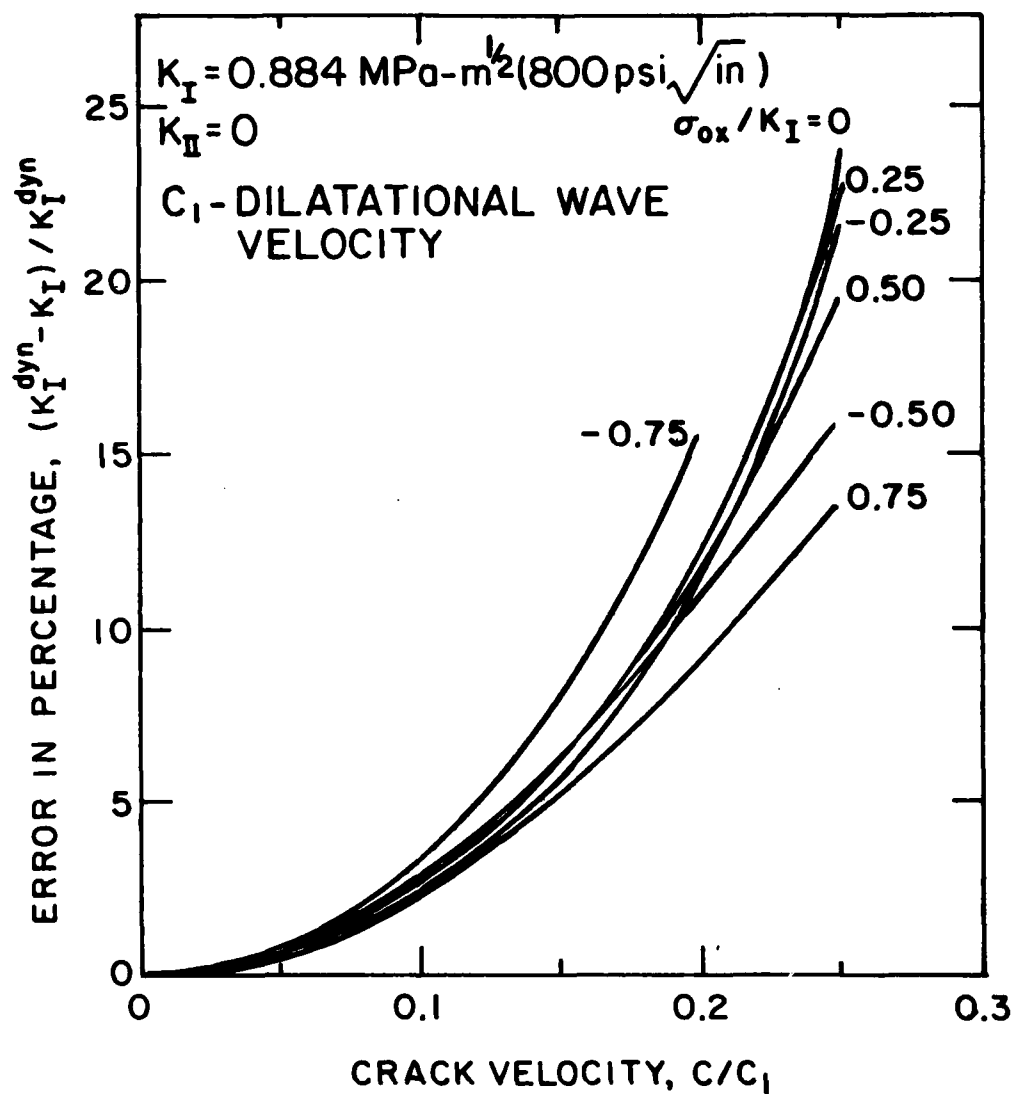


FIGURE 7. ERROR IN DYNAMIC K_I DETERMINATION USING A STATIC TWO-PARAMETER $K_I - \sigma_{ox}$ STRESS FIELD.

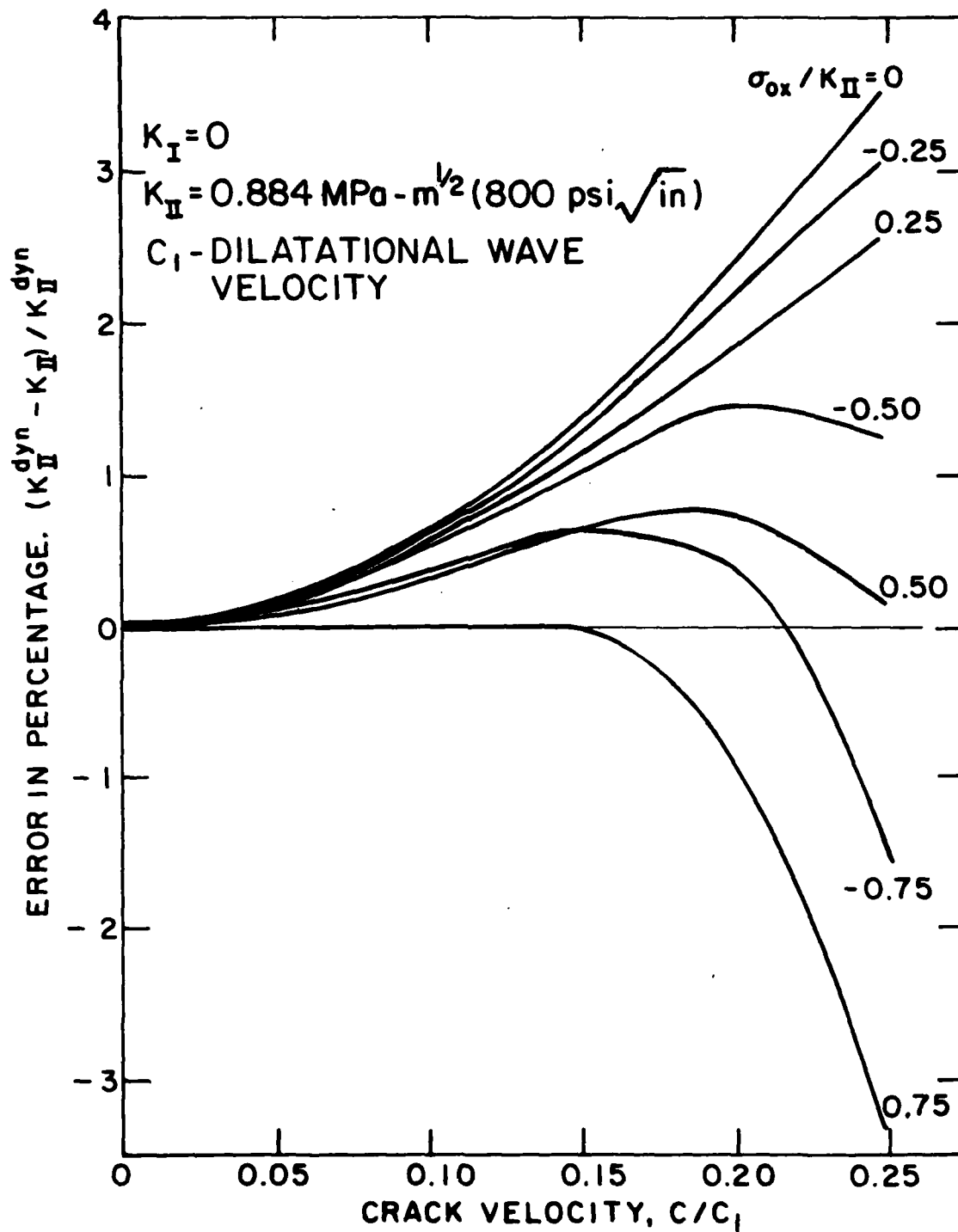


FIGURE 8. ERROR IN DYNAMIC K_{II} DETERMINATION USING A STATIC TWO PARAMETER $K_{II} - \sigma_{0x}$ STRESS FIELD.

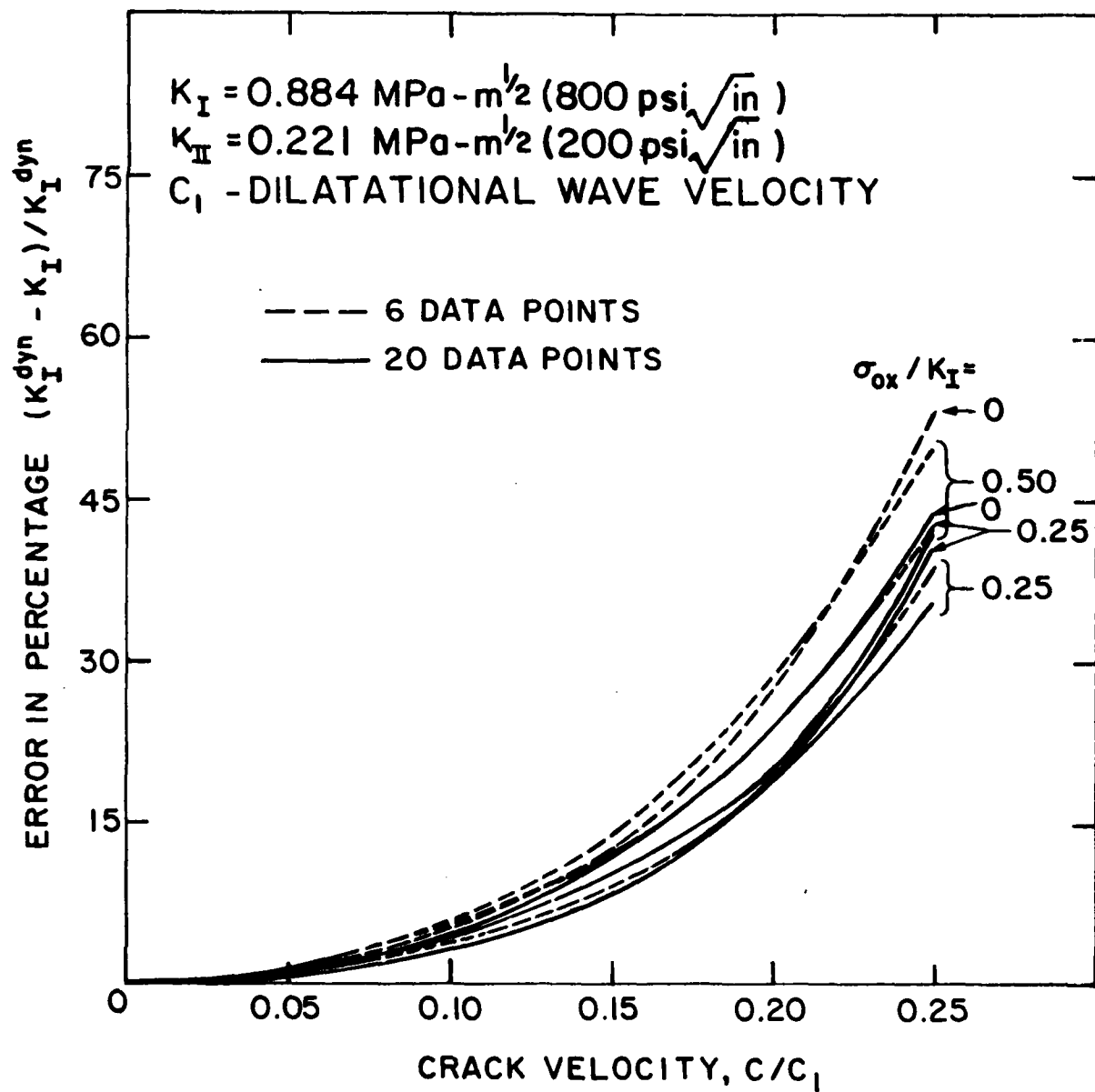


FIGURE 9a. ERRORS IN DYNAMIC K_I DETERMINATION USING A STATIC
 THREE PARAMETER $K_I - K_{II} - \sigma_{ox}$, STRESS FIELD.

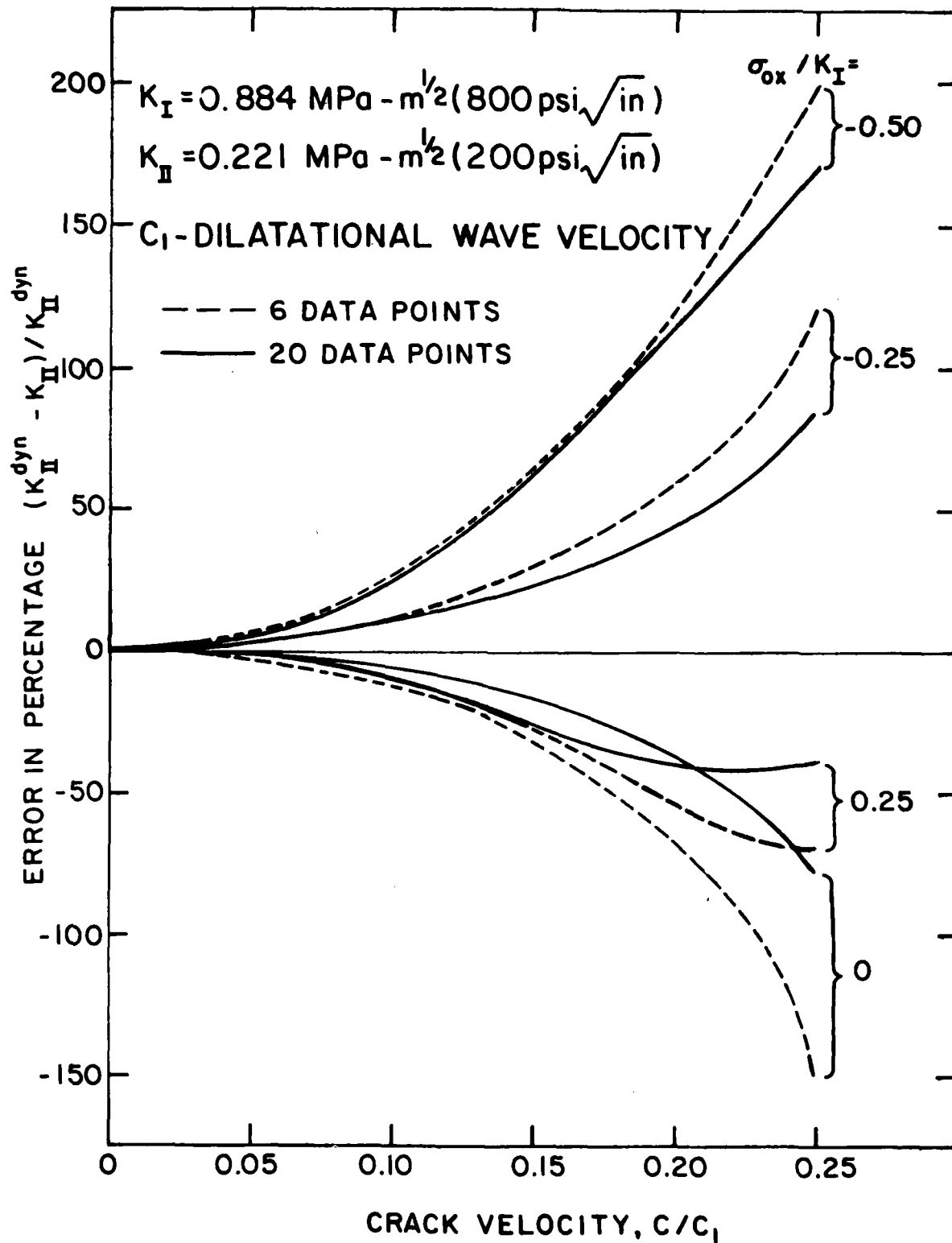


FIGURE 9b . ERRORS IN DYNAMIC K_{II} DETERMINATION USING A STATIC THREE PARAMETER K_I - K_{II} - σ_{ox} , STRESS FIELD.



(a) EIGHTH FRAME 175 μ SECONDS



(b) NINTH FRAME 195 μ SECONDS

FIGURE 10. TYPICAL DYNAMIC PHOTOELASTIC PATTERNS IN HOMALITE-100 SINGLE EDGED NOTCH SPECIMEN (FIXED GRIP LOADING) CRACK APPROACHING A CENTRAL HOLE, NO. W090270.



(a) EIGHTH FRAME 138 μ SECONDS



(b) ELEVENTH FRAME 225 μ SECONDS

FIGURE 11. TYPICAL CRACK BRANCHING DYNAMIC PHOTOELASTIC PATTERNS IN HOMALITE 100 SINGLE EDGEDNOTCH SPECIMEN (FIXED GRIP LOADING), NO. W082270.

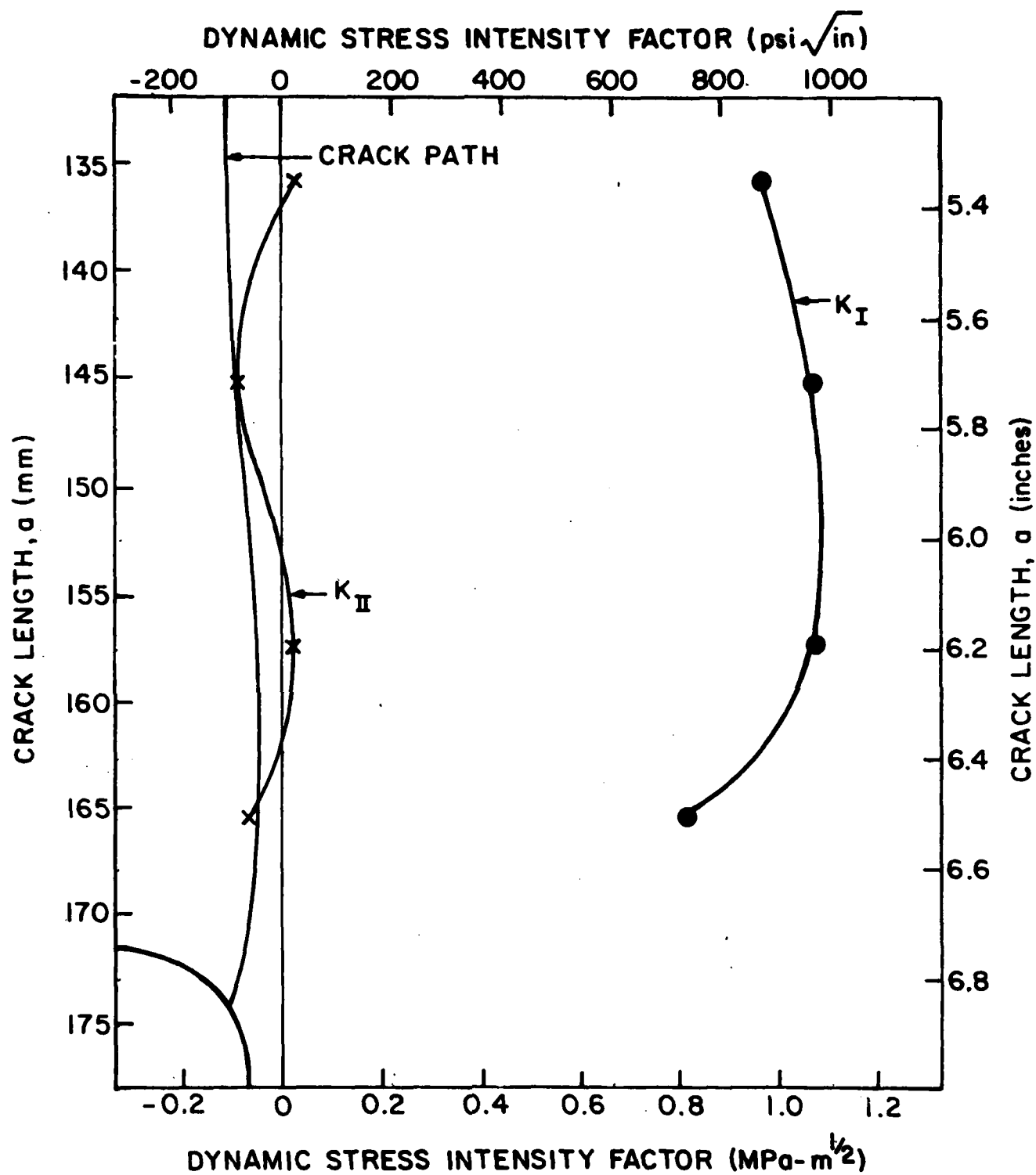


FIGURE 12. DYNAMIC STRESS INTENSITY FACTOR OF CURVED CRACK (FIGURE 10).

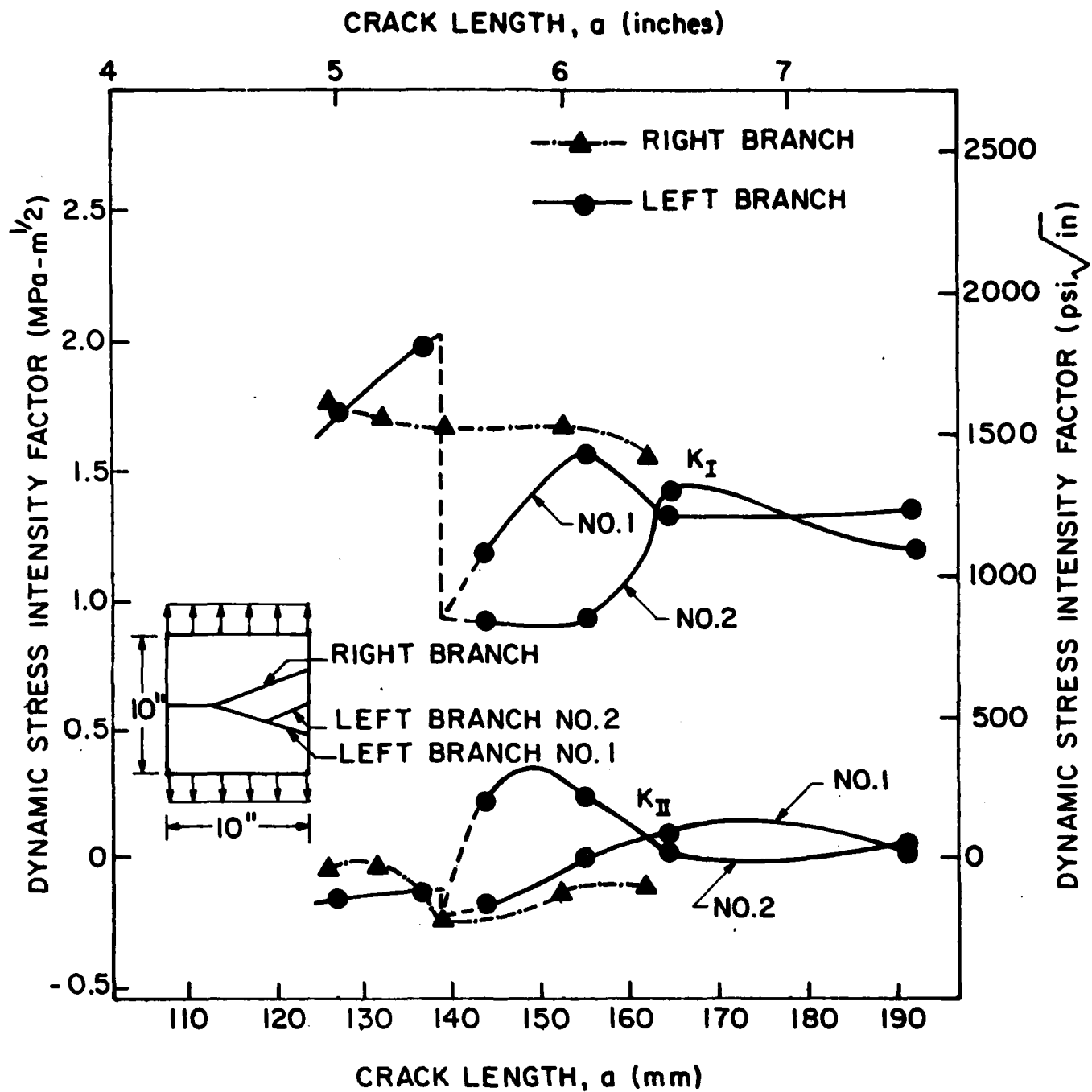


FIGURE 13. DYNAMIC STRESS INTENSITY FACTOR OF A BRANCHED CRACK (FIGURE 11.).

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Applied Sciences
Pasadena, California 91109

Professor Paul M. Naghd
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Berkeley, California 94720

Professor A. J. Durrall
Oakland University
School of Engineering
Rochester, Missouri 64063

Professor F. L. D'Amico
Columbia University
Department of Civil Engineering
New York, New York 10027

Professor Norman Jones
The University of Liverpool
Department of Mechanical Engineering
P. O. Box 147
Browlow Hill
Liverpool L69 3BX
England

Professor E. J. Skudavik
Pennsylvania State University
Applied Research Laboratory
Department of Physics
State College, Pennsylvania 16801

Universities (Con't.)

Professor J. Klossner
Polytechnic Institute of New York
Department of Mechanical and
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333 Jay Street
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Professor R. A. Schapery
Texas A&M University
Department of Civil Engineering
College Station, Texas 77843

Professor Walter D. Pilkey
University of Virginia
Research Laboratories for the
Engineering Sciences and
Applied Sciences
Charlottesville, Virginia 22901

Professor R. D. Millmert
Clarkson College of Technology
Department of Mechanical Engineering
Potomac, New York 13676

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Texas A&M University
Aerospace Engineering Department
College Station, Texas 77843

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University of Arizona
Department of Aerospace and
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Georgia Institute of Technology
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20. ABSTRACT (Continue on reverse side if necessary and identify by block number) The mixed mode, near-field state of stresses surrounding a crack propagating at constant velocity is used to derive a relation between the dynamic stress intensity factors K_I , K_{II} , the remote stress component σ_{ox} and the dynamic isochromatics. This relation together with an overdeterministic least-square method form the basis of a data reduction procedure for		

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extracting dynamic K_I , K_{II} and σ_{OX} from the recorded dynamic photoelastic pattern surrounding a running crack. The overdeterministic least-square method is also used to fit static isochromatics to the numerically generated dynamic isochromatics. The resultant static K_I , K_{II} , and σ_{OX} are compared with the corresponding dynamic values and estimates of errors involved in using static analysis to process dynamic isochromatic data are obtained. The data reduction procedure is then used to evaluate the branching stress intensity factor associated with crack branching and the mixed mode stress intensity factors associated with crack curving.

$K_{\text{sub } I}$; $K_{\text{sub } II}$, and $\sigma_{\text{sub } OX}$

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